

### 5.5 Complex Eigenvalues

**5.5.4. Problem Restatement:** Find the eigenvalues and a basis of the eigenspace in  $\mathbf{C}^2$  of  $A = \begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix}$ .

**Final Answer:** The complex eigenvalues are  $\lambda = 4 + i$  and  $\bar{\lambda} = 4 - i$ . A basis of the eigenspace corresponding to  $\lambda = 4 + i$  is  $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right\}$ , and a basis of the eigenspace corresponding to  $\bar{\lambda} = 4 - i$  is  $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right\}$ .

**Work:** The characteristic polynomial is  $\det(A - \lambda I) = \det \begin{bmatrix} 5 - \lambda & -2 \\ 1 & 3 - \lambda \end{bmatrix} = (5 - \lambda)(3 - \lambda) + 2 = \lambda^2 - 8\lambda + 17$ . The roots of the characteristic polynomial are the complex eigenvalues  $\lambda = (8 + \sqrt{64 - 68})/2 = 4 + i$  and  $\bar{\lambda} = 4 - i$ .  $A - \lambda I = \begin{bmatrix} 5 - (4 + i) & -2 \\ 1 & 3 - (4 + i) \end{bmatrix} = \begin{bmatrix} -1 - i & -2 \\ 1 & -1 - i \end{bmatrix}$ . If  $\begin{bmatrix} z_1 \\ z_2 \end{bmatrix}$  is a complex eigenvector corresponding to  $\lambda = 4 + i$  then  $\begin{bmatrix} -1 - i & -2 \\ 1 & -1 - i \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ , so  $(-1 - i)z_1 - 2z_2 = 0$  and  $z_1 + (-1 - i)z_2 = 0$ . From the second equation, we get  $\begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = z_2 \begin{bmatrix} 1 + i \\ 1 \end{bmatrix} = z_2 \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right)$  with  $z_2$  a free variable. Therefore, a basis of the eigenspace corresponding to  $\lambda = 4 + i$  is  $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right\}$ . To get a basis of the eigenspace corresponding to  $\bar{\lambda} = 4 - i$ , we take the complex conjugate, giving us  $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right\}$  (we can do this because, if  $v$  is a complex eigenvector corresponding to  $\lambda$  then  $\bar{v}$  is a complex eigenvector corresponding to  $\bar{\lambda}$ ).

**Check:** We will test  $Av = (4 + i)v$  for  $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} i$ . The left hand side is  $Av = \begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} i = \begin{bmatrix} 3 \\ 4 \end{bmatrix} + \begin{bmatrix} 5 \\ 1 \end{bmatrix} i$  and the right hand side is  $(4 + i)v = (4 + i) \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right) = \left( \begin{bmatrix} 4 \\ 4 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \right) + \left( \begin{bmatrix} 4 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} i \right) = \begin{bmatrix} 3 \\ 4 \end{bmatrix} + \begin{bmatrix} 5 \\ 1 \end{bmatrix} i$ .

The computed left and right hand sides show  $Av = (4 + i)v$  holds. Thus, the check is successful, verifying that  $v$  is indeed a complex eigenvector corresponding to  $\lambda = 4 + i$ . Since complex conjugation preserves eigenvectors (that is,  $\bar{v}$  is an eigenvector corresponding to  $\bar{\lambda} = 4 - i$ ), we do not need to check the conjugate eigenvector.

**5.5.8. Problem Restatement:** List the eigenvalues of  $A = \begin{bmatrix} \sqrt{3} & 3 \\ -3 & \sqrt{3} \end{bmatrix}$ . The transformation  $x \mapsto Ax$  is the composition of a rotation and a scaling. Find the angle of rotation  $\theta$ , where  $-\pi \leq \theta \leq \pi$ , and find the scaling factor  $r$ .

**Final Answer:** The eigenvalues are  $\lambda = \sqrt{3} - 3i$  and  $\bar{\lambda} = \sqrt{3} + 3i$ . The scaling factor is  $r = \sqrt{3+9} = 2\sqrt{3}$ , and  $\theta = -\pi/3$  since  $\cos \theta = \sqrt{3}/r = 1/2$  and  $\sin \theta = -3/r = -\sqrt{3}/2$ .

**Work:** None required.

**5.5.16. Problem Restatement:** Find an invertible matrix  $P$  and a matrix  $C$  of the form  $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$  such that  $A = PCP^{-1}$ , where  $A = \begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix}$ . Use the information found in exercise 5.5.4.

**Final Answer:** With  $\lambda = 1 + i$ , we get  $C = \begin{bmatrix} 4 & -1 \\ 1 & 4 \end{bmatrix}$  and  $P = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix}$ . (Alternatively, with  $\lambda = 1 - i$ , we get  $C = \begin{bmatrix} 4 & 1 \\ -1 & 4 \end{bmatrix}$  and  $P = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ .)

**Work:** We refer to the work in the solution to 5.5.4.  $\lambda = 4 + i$ , so we set  $C = \begin{bmatrix} 4 & -1 \\ 1 & 4 \end{bmatrix}$ . We use the eigenvector corresponding to  $\bar{\lambda} = 4 - i$  to construct  $P$ . Therefore,  $P = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix}$ .

**Checks:**  $AP = \begin{bmatrix} 3 & -5 \\ 4 & -1 \end{bmatrix} = PC$ .  $\det(P) = 1 \neq 0$ , so  $P$  is invertible. This gives us  $A = PCP^{-1}$ , as required.

**5.5.22. Problem Restatement:** Let  $A$  be a complex (or real)  $n \times n$  matrix, and let  $x \in \mathbf{C}^n$  be an eigenvector corresponding to an eigenvalue in  $\mathbf{C}$ . Show that for every nonzero complex scalar  $\mu$ , the vector  $\mu x$  is an eigenvector of  $A$ .

**Final Answer:** Let  $\mu$  be any nonzero complex scalar, and let  $y = \mu x$ .  $y \neq 0$  because  $\mu \neq 0$  and  $x \neq 0$ . Let  $\lambda$  be the complex eigenvalue corresponding to  $x$ . We have  $Ay = A(\mu x) = \mu Ax = \mu(\lambda x) = \lambda(\mu x) = \lambda y$ . Therefore,  $y$  is an eigenvector of  $A$  corresponding to the eigenvalue  $\lambda$ .

**Work:** None required.

## 6.1 Inner Product, Length, and Orthogonality

**6.1.10. Problem Restatement:** Find a unit vector in the direction of  $v = \begin{bmatrix} -6 \\ 4 \\ -3 \end{bmatrix}$ .

**Final Answer:** A unit vector in the direction of  $v$  is  $u = v/\|v\| = \begin{bmatrix} -6/\sqrt{61} \\ 4/\sqrt{61} \\ -3/\sqrt{61} \end{bmatrix}$ .

**Work:**  $\|v\| = \sqrt{(-6)^2 + 4^2 + (-3)^2} = \sqrt{36 + 16 + 9} = \sqrt{61}$ .

**6.1.14. Problem Restatement:** Find the distance between  $u = \begin{bmatrix} 0 \\ -5 \\ 2 \end{bmatrix}$  and  $z = \begin{bmatrix} -4 \\ -1 \\ 8 \end{bmatrix}$ .

**Final Answer:** The distance between  $u$  and  $z$  is  $\|u - z\| = 2\sqrt{17}$ .

**Work:**  $\|u - z\| = \sqrt{(0 - (-4))^2 + (-5 - (-1))^2 + (2 - 8)^2} = \sqrt{16 + 16 + 36} = \sqrt{68} = 2\sqrt{17}$ .

**6.1.18. Problem Restatement:** Determine if  $y = \begin{bmatrix} -3 \\ 7 \\ 4 \\ 0 \end{bmatrix}$  and  $z = \begin{bmatrix} 1 \\ -8 \\ 15 \\ -7 \end{bmatrix}$  are orthogonal.

**Final Answer:**  $y$  and  $z$  are not orthogonal, since  $y \cdot z \neq 0$ .

**Work:**  $y \cdot z = -3(1) + 7(-8) + 4(15) + 0(-7) = 1 \neq 0$ .

**6.1.24. Problem Restatement:** Verify the *parallelogram law* for vectors  $u$  and  $v$  in  $\mathbf{R}^n$ :

$$\|u + v\|^2 + \|u - v\|^2 = 2\|u\|^2 + 2\|v\|^2.$$

**Final Answer:** See work below.

**Work:** Using the properties of dot product, we have

$$\begin{aligned} \|u + v\|^2 + \|u - v\|^2 &= (u + v) \cdot (u + v) + (u - v) \cdot (u - v) \\ &= u \cdot u + u \cdot v + v \cdot u + v \cdot v + u \cdot u + u \cdot (-v) + (-v) \cdot u + (-v) \cdot (-v) \\ &= u \cdot u + u \cdot v + v \cdot u + v \cdot v + u \cdot u - u \cdot v - v \cdot u + v \cdot v \\ &= 2(u \cdot u) + 2(v \cdot v) \\ &= 2\|u\|^2 + 2\|v\|^2. \end{aligned}$$

## 6.2 Orthogonal Sets

**6.2.2. Problem Restatement:** Determine if  $\left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} \right\}$  is an orthogonal set of vectors.

**Final Answer:** Yes, this is an orthogonal set of vectors.

$$\begin{aligned} \text{Work: } \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} &= 1(0) + (-2)(1) + 1(2) = 0 - 2 + 2 = 0, \\ \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} &= 1(-5) + (-2)(-2) + 1(1) = -5 + 4 + 1 = 0, \text{ and} \\ \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} &= 0(-5) + 1(-2) + 2(1) = 0 - 2 + 2 = 0. \end{aligned}$$

**6.2.6. Problem Restatement:** Determine if  $\left\{ \begin{bmatrix} 5 \\ -4 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} -4 \\ 1 \\ -3 \\ 8 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 5 \\ -1 \end{bmatrix} \right\}$  is an orthogonal set of vectors.

**Final Answer:** The second and third vectors in the set are not orthogonal, so the set is not an orthogonal set of vectors.

$$\text{Work: } \begin{bmatrix} -4 \\ 1 \\ -3 \\ 8 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 3 \\ 5 \\ -1 \end{bmatrix} = (-4)3 + 1(3) + (-3)5 + 8(-1) = -12 + 3 - 15 - 8 = -32 \neq 0.$$

**6.2.10. Problem Restatement:** Show that  $\{u_1, u_2, u_3\}$  is an orthogonal basis of  $\mathbf{R}^3$  and express

$x$  as a linear combinations of the  $u$ 's where  $u_1 = \begin{bmatrix} 3 \\ -3 \\ 0 \end{bmatrix}$ ,  $u_2 = \begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix}$ ,  $u_3 = \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix}$ , and

$$x = \begin{bmatrix} 5 \\ -3 \\ 1 \end{bmatrix}.$$

**Final Answer:**  $u_i \cdot u_j = 0$  for  $i \neq j$ , all  $i = 1, 2, 3$  and  $j = 1, 2, 3$ , as shown in the work below, so  $\{u_1, u_2, u_3\}$  is a linearly independent set of three nonzero orthogonal vectors in  $\mathbf{R}^3$ .

Therefore,  $\{u_1, u_2, u_3\}$  is an orthogonal basis of  $\mathbf{R}^3$ . Also, in the work below we establish  $x = \frac{4}{3}u_1 + \frac{1}{3}u_2 + \frac{1}{3}u_3$ .

**Work:**  $u_1 \cdot u_2 = 3(2) + (-3)(2) + 0(-1) = 0$ ,  $u_1 \cdot u_3 = 3(1) + (-3)1 + 0(4) = 0$ , and  $u_2 \cdot u_3 = 2(1) + 2(1) + (-1)4 = 0$ .  $x = \frac{x \cdot u_1}{u_1 \cdot u_1}u_1 + \frac{x \cdot u_2}{u_2 \cdot u_2}u_2 + \frac{x \cdot u_3}{u_3 \cdot u_3}u_3 = \frac{3(5) + (-3)(-3) + 0(1)}{3^2 + (-3)^2 + 0^2}u_1 + \frac{2(5) + 2(-3) + (-1)(1)}{2^2 + 2^2 + (-1)^2}u_2 + \frac{1(5) + 1(-3) + 4(1)}{1^2 + 1^2 + 4^2}u_3 = \frac{24}{18}u_1 + \frac{3}{9}u_2 + \frac{6}{18}u_3 = \frac{4}{3}u_1 + \frac{1}{3}u_2 + \frac{1}{3}u_3$ .

**6.2.14. Problem Restatement:** Let  $y = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$  and  $u = \begin{bmatrix} 7 \\ 1 \end{bmatrix}$ . Write  $y$  as the sum of two orthogonal vectors, one in  $\text{Span}\{u\}$  and one orthogonal to  $u$ .

**Final Answer:**  $y = \begin{bmatrix} \frac{14}{5} \\ \frac{28}{5} \end{bmatrix} + \begin{bmatrix} -\frac{4}{5} \\ \frac{28}{5} \end{bmatrix}$ .  $\begin{bmatrix} \frac{14}{5} \\ \frac{28}{5} \end{bmatrix} \in \text{Span}\{u\}$  and  $\begin{bmatrix} -\frac{4}{5} \\ \frac{28}{5} \end{bmatrix}$  is orthogonal to  $u$ .

**Work:**  $y = \hat{y} + z$  where the orthogonal projection onto  $\text{Span}\{u\}$  is  $\hat{y} = \frac{y \cdot u}{u \cdot u}u = \frac{14+6}{49+1}u = \frac{20}{50}u = \frac{2}{5}u = \begin{bmatrix} \frac{14}{5} \\ \frac{28}{5} \end{bmatrix}$  and the vector orthogonal to  $u$  is  $z = y - \hat{y} = \begin{bmatrix} 2 \\ 6 \end{bmatrix} - \begin{bmatrix} \frac{14}{5} \\ \frac{28}{5} \end{bmatrix} = \begin{bmatrix} -\frac{4}{5} \\ \frac{28}{5} \end{bmatrix}$ .

### 6.3 Orthogonal Projections

**6.3.2. Problem Restatement:**  $u_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix}$ ,  $u_2 = \begin{bmatrix} -2 \\ 1 \\ -1 \\ 1 \end{bmatrix}$ ,  $u_3 = \begin{bmatrix} 1 \\ 1 \\ -2 \\ -1 \end{bmatrix}$ ,  $u_4 = \begin{bmatrix} -1 \\ 1 \\ 1 \\ -2 \end{bmatrix}$ , and

$v = \begin{bmatrix} 4 \\ 5 \\ -3 \\ 3 \end{bmatrix}$ . Assuming  $\{u_1, u_2, u_3, u_4\}$  is an orthogonal basis of  $\mathbf{R}^4$ , write  $v$  as the sum of two vectors, one in  $\text{Span}\{u_1\}$  and one in  $\text{Span}\{u_2, u_3, u_4\}$ .

**Final Answer:**  $v = x + y$  where  $x = 2u_1 = \begin{bmatrix} 2 \\ 4 \\ 2 \\ 2 \end{bmatrix}$  in  $\text{Span}\{u_1\}$ , and  $y = v - x = \begin{bmatrix} 2 \\ 1 \\ -5 \\ 1 \end{bmatrix}$  in  $\text{Span}\{u_2, u_3, u_4\}$ .

**Work:**  $\text{Span}\{u_1\}$  and  $\text{Span}\{u_2, u_3, u_4\}$  are orthogonal complements of each other, so if  $x$  is the orthogonal projection of  $v$  onto  $\text{Span}\{u_1\}$  then  $y = v - x$  is the orthogonal projection of  $v$  onto  $\text{Span}\{u_2, u_3, u_4\}$ .  $\frac{u_1 \cdot v}{u_1 \cdot u_1} = \frac{1(4) + 2(5) + 1(-3) + 1(3)}{1^2 + 2^2 + 1^2 + 1^2} = \frac{14}{7} = 2$ . Therefore,  $x = 2u_1$  and  $y = v - 2u_1$ .

**6.3.6. Problem Restatement:**  $y = \begin{bmatrix} 6 \\ 4 \\ 1 \end{bmatrix}$ ,  $u_1 = \begin{bmatrix} -4 \\ -1 \\ 1 \end{bmatrix}$ , and  $u_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ . Verify that  $\{u_1, u_2\}$  is an orthogonal set, and then find the orthogonal projection of  $y$  onto  $\text{Span}\{u_1, u_2\}$ .

**Final Answer:**  $u_1 \cdot u_2 = (-4)0 + (-1)1 + 1(1) = 0$ , so  $\{u_1, u_2\}$  is an orthogonal set. The orthogonal projection of  $y$  onto  $\text{Span}\{u_1, u_2\}$  is  $\hat{y} = -\frac{3}{2}u_1 + \frac{5}{2}u_2$ . Since  $-\frac{3}{2}u_1 + \frac{5}{2}u_2 = y$ , we get  $\hat{y} = y$ ; that is  $y \in \text{Span}\{u_1, u_2\}$ .

**Work:**  $\hat{y} = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \frac{y \cdot u_2}{u_2 \cdot u_2} u_2 = \frac{6(-4)+4(-1)+1(1)}{(-4)^2+(-1)^2+1^2} u_1 + \frac{6(0)+4(1)+1(1)}{0^2+1^2+1^2} u_2 = -\frac{27}{18} u_1 + \frac{5}{2} u_2 = -\frac{3}{2} u_1 + \frac{5}{2} u_2$ .

**6.3.12. Problem Restatement:** Find the closest point to  $y = \begin{bmatrix} 3 \\ -1 \\ 1 \\ 13 \end{bmatrix}$  in the subspace  $W$  spanned

$$\text{by } v_1 = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 2 \end{bmatrix} \text{ and } v_2 = \begin{bmatrix} -4 \\ 1 \\ 0 \\ 3 \end{bmatrix}.$$

**Final Answer:** the closest point to  $y =$  in the subspace  $W$  spanned by  $v_1 =$  and  $v_2$  is

$$\hat{y} = \frac{y \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{y \cdot v_2}{v_2 \cdot v_2} v_2 = 3v_1 + v_2 = \begin{bmatrix} -1 \\ -5 \\ -3 \\ 9 \end{bmatrix}.$$

**Check:** If  $z = y - \hat{y} = 4 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ , then it is easy to see  $z$  is orthogonal to  $v_1 =$  and  $v_2$ .

**Work:**

$$v_1 \cdot v_2 = (1)(-4) + (-2)(1) + (-1)(0) + (2)(3) = 0, \text{ so } v_1 \perp v_2.$$

$$y \cdot v_1 = (3)(1) + (-1)(-2) + (1)(-1) + (13)(2) = 30.$$

$$y \cdot v_2 = (3)(-4) + (-1)(1) + (1)(0) + (13)(3) = 26.$$

$$v_1 \cdot v_1 = (1)^2 + (-2)^2 + (-1)^2 + (2)^2 = 10.$$

$$v_2 \cdot v_2 = (-4)^2 + (1)^2 + (0)^2 + (3)^2 = 26.$$

$$\frac{y \cdot v_1}{v_1 \cdot v_1} = 3, \text{ and } \frac{y \cdot v_2}{v_2 \cdot v_2} = 1.$$

**6.3.14. Problem Restatement:** Find the best approximation to  $z$  by vectors of the form

$$c_1v_1 + c_2v_2, \text{ where } z = \begin{bmatrix} 2 \\ 4 \\ 0 \\ -1 \end{bmatrix}, v_1 = \begin{bmatrix} 2 \\ 0 \\ -1 \\ -3 \end{bmatrix}, \text{ and } v_2 = \begin{bmatrix} 5 \\ -2 \\ 4 \\ 2 \end{bmatrix}$$

**Final Answer:**  $\{c_1v_1 + c_2v_2 \mid c_1, c_2 \in \mathbf{R}\} = \text{Span}\{v_1, v_2\}$ . Therefore, the best approximation

to  $z$  by vectors of the form  $c_1v_1 + c_2v_2$  is  $\hat{z} = \frac{z \cdot v_1}{v_1 \cdot v_1}v_1 + \frac{z \cdot v_2}{v_2 \cdot v_2}v_2 = \frac{1}{2}v_1 + 0v_2 = \frac{1}{2} \begin{bmatrix} 2 \\ 0 \\ -1 \\ -3 \end{bmatrix}$ .

**Check:** If  $u = z - \hat{z} = \begin{bmatrix} 1 \\ 4 \\ \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$ , then it is easy to see  $u \perp v_1$  and  $u \perp v_2$ .

**Work:**

$$v_1 \cdot v_2 = (2)(5) + (0)(-2) + (-1)(4) + (-3)(2) = 0, \text{ so } v_1 \perp v_2.$$

$$z \cdot v_1 = (2)(2) + (4)(0) + (0)(-1) + (-1)(-3) = 7.$$

$$z \cdot v_2 = (2)(5) + (4)(-2) + (0)(4) + (-1)(2) = 0.$$

$$v_1 \cdot v_1 = (2)(2) + (0)(0) + (-1)(-1) + (-3)(-3) = 14.$$

$$v_2 \cdot v_2 = (5)(5) + (-2)(-2) + (4)(4) + (2)(2) = 34.$$

$$c_1 = \frac{v_1 \cdot z}{v_1 \cdot v_1} = \frac{1}{2}, \text{ and } c_2 = \frac{v_2 \cdot z}{v_2 \cdot v_2} = 0.$$

## 6.7 Inner Product Spaces

**6.7.4. Problem Restatement:** Let  $\mathbf{P}_2$  have inner product defined by evaluation at  $-1, 0,$  and  $1$  (that is,  $\langle p(t), q(t) \rangle = p(-1)q(-1) + p(0)q(0) + p(1)q(1)$ ). Compute  $\langle p(t), q(t) \rangle$  where  $p(t) = 3t - t^2$ , and  $q(t) = 3 + 2t^2$ .

**Final Answer:**  $\langle p(t), q(t) \rangle = (3(-1) - (-1)^2)(3 + 2(-1)^2) + (3(0) - (0)^2)(3 + 2(0)^2) + (3(1) - (1)^2)(3 + 2(1)^2) = (-4)(5) + (0)(3) + (2)(5) = -10$ .

**Work:** None required.

**6.7.6. Problem Restatement:** Compute  $\|p\|$  and  $\|q\|$ , for  $p$  and  $q$  in 6.7.4.

**Final Answer:**  $\|p\| = 2\sqrt{5}$ , and  $\|q\| = \sqrt{59}$ .

**Work:**  $\|p\|^2 = \langle p(t), p(t) \rangle = (-4)^2 + 0^2 + 2^2 = 20$ , and  $\|q\|^2 = \langle q(t), q(t) \rangle = 5^2 + 3^2 + 5^2 = 59$ .

**6.7.8. Problem Restatement:** Find the orthogonal projection of  $q$  onto  $\text{Span}\{p\}$ , for  $p$  and  $q$  in 6.7.4.

**Final Answer:** Find the orthogonal projection of  $q$  onto  $\text{Span}\{p\}$  is

$$\hat{q} = \frac{\langle q, p \rangle}{\langle p, p \rangle} p = -\frac{10}{20}(3t - t^2) = -\frac{3}{2}t + \frac{1}{2}t^2.$$

**Work:** None required.

**6.7.10. Problem Restatement:** Let  $\mathbf{R}_3$  have inner product given by evaluation at  $-3, -1, 1,$  and  $3$ . Let  $p_0(t) = 1, p_1(t) = t,$  and  $q(t) = t^2 - 5$  (found in the back of text). Find the best approximation to  $t^3$  by polynomials in  $\text{Span}\{p_0, p_1, q\}$ .

**Final Answer:** According to the information given in 4.7.9,  $\{p_0, p_1, q\}$  is an orthogonal set.

Therefore, the best approximation to  $t^3$  by polynomials in  $\text{Span}\{p_0, p_1, q\}$  is

$$\hat{t^3} = \frac{\langle t^3, p_0 \rangle}{\langle p_0, p_0 \rangle} p_0 + \frac{\langle t^3, p_1 \rangle}{\langle p_1, p_1 \rangle} p_1 + \frac{\langle t^3, q \rangle}{\langle q, q \rangle} q = \frac{0}{4} p_0 + \frac{164}{20} p_1 + \frac{0}{64} q = \frac{41}{5} p_1 = \frac{41}{5} t.$$

**Work:**

$$\langle p_0, p_0 \rangle = 1^2 + 1^2 + 1^2 + 1^2 = 4.$$

$$\langle p_1, p_1 \rangle = (-3)^2 + (-1)^2 + (1)^2 + (3)^2 = 20.$$

$$\langle q, q \rangle = (4)^2 + (-4)^2 + (-4)^2 + (4)^2 = 64.$$

$$\langle t^3, p_0 \rangle = (-3)^3(1) + (-1)^3(1) + (1)^3(1) + (3)^3(1) = 0.$$

$$\langle t^3, p_1 \rangle = (-3)^3(-3) + (-1)^3(-1) + (1)^3(1) + (3)^3(3) = 164.$$

$$\langle t^3, q \rangle = (-3)^3(4) + (-1)^3(-4) + (1)^3(-4) + (3)^3(4) = 0.$$